

Analytical Modeling of Uplink Cellular Networks

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Abstract

Cellular uplink analysis has typically been undertaken by either a simple approach that lumps all interference into a single deterministic or random parameter in a Wyner-type model, or via complex system level simulations that often do not provide insight into why various trends are observed. This paper proposes a novel middle way using point processes that is both accurate and also results in easy-to-evaluate integral expressions based on the Laplace transform of the interference. We assume mobiles and base stations are randomly placed in the network with each mobile pairing up to its closest base station. Compared to related recent work on downlink analysis, the proposed uplink model differs in two key features. First, dependence is considered between the user and base station point processes to make sure each base station serves a single mobile in the given resource block. Second, per-mobile power control is included, which further couples the transmission of mobiles due to location dependent channel inversion. Nevertheless, we succeed in deriving the coverage (equivalently outage) probability of a typical link in the network. This model can be used to address a wide variety of system design questions in the future. In this paper we focus on the implications for power control and see that partial channel inversion should be used at low SINR, while full power transmission is optimal at higher SINR.

I. INTRODUCTION

Modern cellular networks are evolving from voice-oriented to ubiquitous mobile-broadband data networks. While the downlink of these networks typically drives their bandwidth and speed

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requirements, improvements in uplink performance are increasingly important due to symmetric traffic applications like social networking, video-calls, and real-time generation and sharing of media content. A complete analytical framework for the cellular uplink requires several fundamental changes to the system model compared to the downlink, nearly all of which make analysis more difficult. While interference in the downlink comes from the fixed locations, in the uplink, interference is generated by mobile devices distributed throughout the network. A second distinction is the use of location dependent power control, which makes the transmit power highly variable, and therefore significantly changes the interference statistics compared to the downlink. Additionally, for the uplink, both a maximum power constraint and consideration of average transmit power are especially important for battery powered user devices. These constraints and their interdependence have made analysis of the uplink very challenging using traditional approaches. This work presents to our knowledge the first non-trivial tractable model for determining the fundamental metric of uplink performance, the complete Signal to Interference Plus Noise Ratio (SINR) distribution. Using tools from stochastic geometry and point process theory, this SINR distribution immediately gives coverage and outage probability and allows rate to be easily computed as well.

A. Uplink Modeling Approaches

One approach for analysis of the uplink has been to use the Wyner model [2]. It is attractive for its analytical simplicity, wherein gains between users and base stations are normalized by the desired link and inter-cell interference is either a constant value or a single random variable to account for fading. Historically popular for evaluating CDMA-based networks, this model is still used to evaluate performance from an information-theory perspective including multi-cell processing techniques [3]–[8]. However, in [9] the applicability and accuracy of the model is shown to be limited to scenarios where the interference can be spatially averaged, for example a CDMA network under high load. This type of interference averaging approach wherein inter-cell interference is assumed to be fixed is not a valid assumption for modern cellular systems where typically only a single user per cell (or sector) is active in a given resource block.

On the other extreme from the Wyner model, base stations are commonly modeled in a deterministic grid-based deployment, e.g. the popular hexagonal grid model. This approach does not lead to a tractable framework and results are based upon several simplifying approximations

followed by exhaustive Monte Carlo simulations. Perhaps more importantly, the grid model – which was always highly idealized – is particularly out-of-touch with ongoing deployments, which have highly variable cell sizes and opportunistic placement of new towers [10], [11].

The inadequacy of existing approaches has led to an increased interest in the use of random spatial models for the network topology [12]. An advantage of this new approach is the ability to derive tractable expressions leading to more general performance characterizations and intuition [13]–[21]. In our recent work [15], we showed that a completely random (Poisson) placement of base stations was about as accurate as a grid model, and sometimes more so, when compared to a large modern cellular network. Recent work in [22] further illustrated that the PPP model can provide more accurate SINR statistics for actual urban deployments. While this approach has mostly been applied to the downlink, recent work has also attempted to extend this to the uplink by deriving some approximate results for interference limited networks [23]. Under assumptions of multiple users per-base station transmitting on the same frequency CDMA-style and averaged transmit power for the interference the authors of [23] derive analytical expressions for average spectral efficiency as the numbers of antennas, base stations, and users grow asymptotically large.

B. Power Control

Power control in various forms has been one of the key system design features for past, current, and proposed wireless standards [24], [25]. Fast uplink power control has been an especially important feature in CDMA-based networks [26]–[29]. One reason for this is to mitigate the “near-far” problem that occurs when a base station cannot decode the signals of cell-edge users due to the much greater received power (and thus interference) caused by cell-interior users. For modern OFDMA-based cellular networks, due to the orthogonality of per-cell resources removing intra-cell interference and the aggressive use of adaptive modulation and coding techniques, fast power control is not as important of a feature. Instead, slow power control is typically considered, which attempts to overcome pathloss and large-scale fading (shadowing). For example, the 3GPP-LTE standard supports the utilization of open and closed-loop fractional power control in the uplink [30], [31]. While having an impact on coverage and rate, both by overcoming path loss and reshaping the distribution of the interference power, power control is also an important factor for battery utilization. Without a tractable analytical model it is difficult to gain intuition or

quantitative results from a system/network design perspective due to the complicated relationship between the relevant parameters.

Recent work on the use of power control in modern OFDMA-based networks has focused on evaluating performance of different power control algorithms for a given set of system parameters via intensive simulations. The authors of [32] evaluated the impact of the maximum transmit power on open and closed-loop algorithms. In [33], the authors investigate the use of fractional power control in the uplink as a method for maintaining constant interference power at the base station. Maintaining constant interference power is of interest for many practical receiver algorithms which attempt to mitigate the impact of the interference but typically require either knowledge of the interference power or require it to be roughly constant. However a fundamental assumption of these approaches, along with several earlier ones in [34], [35] is the standard regular hexagonal model for base station locations and as a result the results are produced via simulation for only a few sets of possible design parameters.

Very recent work by the authors of [36] proposes an analytical approach to this problem, with a particular goal of giving insight into the selection of fractional power control parameters. They consider a grid deployment for the base station locations and utilize a so-called “fluid” model which approximates the interference received in the center cell as coming from outside cells with the base stations located on rings of fixed radii [37]. Under these assumptions they develop expressions for the SINR and spectral efficiency for users at relative cell-edge and cell-center locations and use these to infer optimal power control parameters.

C. Contributions

The main contribution of this work is the derivation of uplink coverage probability for a randomly chosen mobile user with fractional power control, which is a general power control framework that incorporates virtually all modern cellular systems. We model the locations of the mobile users as a realization of the Poisson Point Process (PPP) and then assume that the base station corresponding to each mobile user is located uniformly in its Voronoi cell [38]. The uplink analysis is significantly more involved than its downlink counterpart because of this location dependence. Furthermore, the transmit power of a mobile in the uplink depends upon the distance to its associated base station due to the fractional power control. It turns out that the random variables denoting this distance for each mobile user are identically distributed

but not independent in general. This dependence is not easy to model accurately and hence leads to further technical challenges in the derivation of the coverage probability. However, we demonstrate that this dependence is weak and can be ignored, which improves the tractability of the system model with minimal impact on the accuracy of the results. Under this assumption, we derive analytical expression for the coverage probability of a randomly chosen mobile user. We further show that the same framework can be used to derive uplink coverage probability of a “regular” base station deployment by considering appropriate distribution of the distances of the interfering mobiles to their serving base stations. Interestingly, this analytical result closely approximates the coverage probability computed numerically for the hexagonal grid model. We comment more on these observations in Section III.

After a discussion of the derived expressions for coverage and average rate we present system design guidelines comparing downlink and uplink coverage and evaluate coverage probability and transmit power utilization as a function of the power control parameters. These results quantify the tradeoff between improved cell-edge SINR for low and moderate values of the fractional power control factor with significant overall power reduction available if power control is more aggressively applied. In the next section, we give our system model and discuss important underlying assumptions.

II. SYSTEM MODEL

A. System Setup and Modeling Assumptions

We consider the uplink of a cellular network utilizing an orthogonal multiple access technique composed of a single class of base stations, macro base stations for example, and focus on the received SINR at a randomly chosen base station. Fig. 1 gives a visual representation of the uplink system model and relationship between parameters. The mobile user locations are assumed to form a realization of a homogeneous two-dimensional spatial PPP [38] with density λ . The spatial PPP corresponds to a uniform distribution of users in the network, which is the baseline assumption for most cellular network system studies [39]. We assume that a mobile user is connected to the closest base station, corresponding to an association metric of max-received power averaged over fading, and that each base station has an active uplink user scheduled. Under such an assumption, it is reasonable to assume that each base station is uniformly distributed in the Voronoi cell of its corresponding mobile user. We perform analysis on a randomly chosen

base station. The distance of this base station to the closest mobile is denoted by a random variable R . For tractability, we will approximate this choice with a case where the analysis is performed on a point uniformly chosen in \mathbb{R}^2 . It is worth noting that there is a subtle difference between the random choice of a base station and a point uniformly chosen in \mathbb{R}^2 due to coupling induced by the dependence in the mobile and the base station point processes. To understand this difference, recall that a point uniformly chosen in \mathbb{R}^2 is biased to lie in bigger Voronoi cells more frequently, whereas there is no such bias when a base station is chosen randomly from the set of base stations. Nevertheless, we show that the base station selection approximation is tight in the context of the performance metrics of coverage and rate considered in this paper. The assumption is formally stated next.

Assumption 1: For tractability, we approximate the choice of a randomly chosen BS from a set of BSs defined such that exactly one BS falls in the Voronoi cell of each mobile by a point uniformly chosen in \mathbb{R}^2 .

Under the above assumption, the random variable R can be shown to be Rayleigh distributed. The proof follows from the null probability of a two dimensional PPP [38] as follows:

$$\mathbb{P}[R > r] = \mathbb{P}[\text{No mobile is in the circle of area } \pi r^2] = e^{-\lambda \pi r^2}, \quad (1)$$

from which the probability density function (pdf) of R follows:

$$f_R(r) = 2\pi\lambda r e^{-\lambda\pi r^2}, \quad r \geq 0. \quad (2)$$

To model uplink interference the location of a randomly chosen base station is considered for convenience to be at the origin, which follows from translation invariance of the point process under Assumption 1. We denote the set of interfering mobiles by \mathcal{Z} , the distance of an interfering mobile $z \in \mathcal{Z}$ to the base station of interest by D_z and the distance of the interfering mobile to its serving base station by R_z . It should be noted that the random variables $\{R_z\}_{z \in \mathcal{Z}}$ are identically distributed but not independent in general. The dependence is induced by the structure of Poisson-Voronoi tessellation and the restriction that only one base station can lie in each Voronoi cell. To visualize this dependence, recall a simple fact that the presence of a base station in a particular Voronoi cell forbids the presence of any other base station in that cell. However, as discussed in detail in the next section, this dependence is weak, which motivates the following independence assumption.

Assumption 2 (Independence Assumption): We assume that the random variables $\{R_z\}_{z \in \mathcal{Z}}$ are independent and identically distributed (i.i.d.).

For the marginal distribution of R_z , we make the following assumption, which lends tractability to uplink analysis both in the case of non-uniform and regular coverage regions. Both these cases will be discussed in detail in the next section.

Assumption 3 (Distribution of R_z): The random variable R_z is assumed to be:

- (a) Rayleigh distributed in the case when we study “irregular” deployment of base stations, i.e., non-uniform coverage regions, and
- (b) Uniformly distributed in the case when we study regular deployment of the base stations, in particular the one corresponding to the hexagonal grid model.

The Rayleigh distribution is motivated by the same null probability argument given in the case of R . Further details and the motivation behind uniform distribution will be given in the next section.

B. Channel Model

To model the channel, the path loss is assumed to be inversely proportional to distance with the path loss exponent given by α . We consider small-scale Rayleigh fading between the mobiles and the base station under consideration, and a constant baseline mobile transmit power of μ^{-1} . Thus the received power of the desired signal at the serving base station is given by $gR^{-\alpha}$, where g is i.i.d. exponentially distributed with mean μ^{-1} . The noise power is assumed to be σ^2 . Next, we assume that all the mobiles utilize distance-proportional fractional power control of the form $R_z^{\alpha\epsilon}$, where $\epsilon \in [0, 1]$ is the power control factor. Thus, as a user moves closer to the desired base station, the transmit power required to maintain the same received signal power decreases, which is an important consideration for battery-powered mobile devices. Under this system model, the associated Signal to Interference Plus Noise Ratio (SINR) at a base station located at origin is

$$\text{SINR} = \frac{gR^{\alpha(\epsilon-1)}}{\sigma^2 + I_{\mathcal{Z}}}, \quad (3)$$

where for an interfering set of mobiles \mathcal{Z} ,

$$I_{\mathcal{Z}} = \sum_{z \in \mathcal{Z}} (R_z^{\alpha})^{\epsilon} g_z D_z^{-\alpha}. \quad (4)$$

If $\epsilon = 1$, the numerator of (3) becomes g , with the pathloss completely inverted by the power control, and if $\epsilon = 0$ no channel inversion is performed and all the mobiles transmit with the same power.

C. Summary of Special Cases

To validate the assumptions and highlight the importance of this model, we will compare the proposed model with various other approaches and special cases. For clarity, we describe all these approaches and special cases below:

PPP: This corresponds to the proposed model without any assumptions, i.e., mobile locations correspond to a spatial PPP with a single base station dropped uniformly within the Voronoi cell of each mobile. Due to dependence induced by the structure of Poisson-Voronoi tessellation, direct analysis of this approach is daunting and hence not given. The numerical results will be provided for this case to validate various approximations leading to the following special cases.

PPP-Rayleigh: Setup is same as the PPP case described above. For tractability we assume R is Rayleigh distributed along with Assumptions 2 and 3(a), i.e., $\{R_z\}$ are i.i.d. Rayleigh distributed. This case leads to the main result corresponding to the irregular base station deployment studied in Section III-A.

PPP-Uniform: This case differs from PPP-Rayleigh only in terms of the distribution of R_z , which is assumed to be uniform in stead of Rayleigh in this case, i.e., assumption 3(b) is taken instead of 3(a). This case leads to the main result corresponding to the regular base station deployment studied in Section III-B.

Grid: To compare the results of the proposed tractable model, we consider the popular grid model, where the base stations are located on the centers of a hexagonal grid and one mobile user is distributed uniformly in each cell. Since this model does not lead to tractable expressions it is evaluated via Monte-Carlo simulations.

Log-normal: This approach approximates inter-cell interference as a log-normal random variable with parameters determined through a numerical fit using simulations of the grid model. It has been utilized in previous works on coverage and capacity analysis for cellular networks due to empirical observations and its relative simplicity [40], [41].

III. COVERAGE PROBABILITY

The probability of coverage can be formally defined as the complementary cumulative distribution function (ccdf) of SINR as:

$$p_c = \mathbb{P}[\text{SINR} > T], \quad (5)$$

which is the probability that the uplink SINR at a randomly chosen base station is greater than the target SINR T . It can also be visualized as being the average area or the average fraction of users in coverage. As noted earlier, we perform analysis on a randomly chosen base station assumed to be located at the origin that connects to the closest mobile user. Under assumption 1, the distribution of the distance of the closest mobile from the randomly chosen base station R can be approximated by the Rayleigh distribution given by (2). As we discuss in detail for R_z later in this section, this approximation is tight and does not affect the accuracy of our results.

The net interference at a randomly chosen base station is the sum of the powers from all the transmitting mobiles lying farther than R . As described in the previous section, this power depends upon the distance of a mobile to its corresponding base station and the power control factor $\epsilon \in [0, 1]$. For a mobile $z \in \mathcal{Z}$, we denote its distance to the corresponding base station as R_z . As stated in the previous section, the random variables $\{R_z\}_{z \in \mathcal{Z}}$ are identically distributed but not independent in general. However, as discussed in detail later in this section, this dependence is weak and we will henceforth assume each R_z to be independent and identically distributed (i.i.d.). Under this independence assumption (Assumption 2), we first derive the coverage probability for the general distribution of R_z and then use this general result to study two particular scenarios corresponding to non-uniform and regular coverage regions. The main uplink coverage probability result of this paper is stated in Theorem 1.

Theorem 1 (Uplink coverage for i.i.d. R_z): The uplink coverage probability is given by:

$$p_c(T, \lambda, \alpha, \epsilon) = 2\pi\lambda \int_0^\infty r e^{-\pi\lambda r^2 - Tr^{\alpha(\epsilon-1)}\sigma^2} \mathcal{L}_{I_z}(Tr^{\alpha(1-\epsilon)}) dr, \quad (6)$$

where the Laplace transform of the interference is given by

$$\mathcal{L}_{I_z}(s) = \exp\left(-2\pi\lambda \int_r^\infty \left(1 - \mathbb{E}_{R_z}\left[\frac{1}{1 + sR_z^{\alpha\epsilon}x^{-\alpha}}\right]\right) x dx\right). \quad (7)$$

Proof: Starting from the definition of p_c and SINR,

$$p_c(T, \lambda, \alpha, \epsilon) = \int_0^\infty \mathbb{P}(\text{SINR} > T) f_R(r) dr \quad (8)$$

$$= \int_0^\infty \mathbb{P} \left(\frac{g(r^{\alpha(\epsilon-1)})}{\sigma^2 + I_Z} > T \right) 2\pi\lambda r e^{-\pi\lambda r^2} dr \quad (9)$$

$$= \int_0^\infty \mathbb{P} \left(g > \frac{T(\sigma^2 + I_Z)}{r^{\alpha(\epsilon-1)}} \right) 2\pi\lambda r e^{-\pi\lambda r^2} dr \quad (10)$$

$$\stackrel{(a)}{=} \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} e^{-Tr^{\alpha(1-\epsilon)}\sigma^2} \mathbb{E}_{I_Z} \left[e^{-Tr^{\alpha(1-\epsilon)}I_Z} \right] dr \quad (11)$$

$$\stackrel{(b)}{=} \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} e^{-Tr^{\alpha(1-\epsilon)}\sigma^2} \mathcal{L}_{I_Z} (Tr^{\alpha(1-\epsilon)}) dr, \quad (12)$$

where (a) follows from the fact that $g \sim \exp(1)$ and (b) follows from the definition of Laplace transform of interference $\mathcal{L}_{I_Z}(s) = \mathbb{E}_{I_Z}[e^{-sI_Z}]$. To complete the proof, we now derive an expression for $\mathcal{L}_{I_Z}(s)$ below:

$$\mathcal{L}_{I_Z}(s) = \mathbb{E}_{I_Z} \left[\exp \left(- \sum_{z \in \mathcal{Z}} s R_z^{\alpha\epsilon} g_z D_z^{-\alpha} \right) \right] \quad (13)$$

$$= \mathbb{E}_{R_z, g_z, D_z} \left[\prod_{z \in \mathcal{Z}} \exp(-s R_z^{\alpha\epsilon} g_z D_z^{-\alpha}) \right] \quad (14)$$

$$\stackrel{(a)}{=} \mathbb{E}_{R_z, D_z} \left[\prod_{z \in \mathcal{Z}} \mathbb{E}_{g_z} [\exp(-s R_z^{\alpha\epsilon} g_z D_z^{-\alpha})] \right] \quad (15)$$

$$\stackrel{(b)}{=} \mathbb{E}_{D_z} \left[\prod_{z \in \mathcal{Z}} \mathbb{E}_{R_z} \left[\frac{1}{1 + s R_z^{\alpha\epsilon} D_z^{-\alpha}} \right] \right] \quad (16)$$

$$\stackrel{(c)}{=} \exp \left(-2\pi\lambda \int_r^\infty \left(1 - \mathbb{E}_{R_z} \left[\frac{1}{1 + s R_z^{\alpha\epsilon} x^{-\alpha}} \right] \right) x dx \right), \quad (17)$$

where (a) follows from the independence of g_z , (b) follows from the independence of R_z and from the fact that $g_z \sim \exp(1)$, and (c) follows from the Probability Generating Functional (PGFL) of a PPP [38]. ■

The coverage probability expression can be simplified for the full power control case ($\epsilon = 1$) in the interference-limited scenario (inter-mobile interference dominates thermal noise), which is stated as the following corollary of Theorem 1.

Corollary 1: The uplink coverage probability for the full power control case ($\epsilon = 1$) assuming no noise ($\sigma^2 = 0$) is given by

$$p_c(T, \lambda, \alpha, \epsilon = 1) = \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} \mathcal{L}_{I_Z}(T) dr, \quad (18)$$

where $\mathcal{L}_{I_Z}(s)$ is a function of r and is given by (17) with $\epsilon = 1$.

A. Distribution of R_z and Comments on Independence Assumption

After deriving the coverage probability expressions for general R_z , we now derive the distribution of R_z for the PPP model under the independence assumption. As mentioned in the previous section, each base station is randomly located in the Voronoi-cell of its corresponding mobile. Therefore, as was done in case of R , R_z can also be approximated by the distance of a randomly chosen point in \mathbb{R}^2 to its closest base station and hence its distribution can be approximated by Rayleigh distribution (as derived for R):

$$f_{R_z}(r_z) = 2\pi\lambda r_z e^{-\lambda\pi r_z^2}, \quad r_z \geq 0 \quad (19)$$

The CCDF of R_z is then $\mathbb{P}[R_z > r_z] = e^{-\lambda\pi r_z^2}$, which is shown to be a tight fit for the numerical estimate for the PPP model in Fig. 2. This is essentially Assumption 3(a) mentioned in the previous section and will be used to specialize Theorem 1 for the case of non-uniform coverage regions, i.e., irregular base station deployment. Although Fig. 2 shows that our approximations for the distributions of R and R_z are tight, it does not provide any insight into the extent of dependence between random variables $\{R_z\}_{z \in \mathcal{Z}}$ which is defined by their joint distribution. Since it is hard to gain insights from the complete joint distribution of $\{R_z\}_{z \in \mathcal{Z}}$, we study a simplified case of the joint distribution of two random variables R_{z_1} and R_{z_2} , which are the distances of the mobiles to their respective base stations in two neighboring Voronoi cells. Since the dependence is expected to be strongest for the neighboring cells, this study can be thought of as a worst case study. We numerically compute the joint pdf $f_{R_{z_1}, R_{z_2}}(r_{z_1}, r_{z_2})$ for the actual PPP model and compare it with the joint pdf derived under the independence assumption in Fig. 3. It should be noted that the joint pdf under the independence condition follows directly from (19) and is given by:

$$f_{R_{z_1}, R_{z_2}}(r_{z_1}, r_{z_2}) = (2\pi\lambda)^2 r_{z_1} r_{z_2} e^{-\lambda\pi(r_{z_1}^2 + r_{z_2}^2)}, \quad r_{z_1} \geq 0, r_{z_2} \geq 0. \quad (20)$$

From Fig. 3, we note that the two joint densities are surprisingly similar, with the pdf slightly more dispersed in the case of the independence assumption, which is the expected direct result of independence. For better visualization, we also provide the top view of the joint densities in Fig. 4, which leads to the same conclusion. The correlation coefficient $\rho_{R_{z_1}, R_{z_2}}$ is numerically computed to be 0.07 for this simulation setup.

After validating the independence assumption, we now use the density of R_z , given by (19), to derive the Laplace transform of interference for the PPP case, which is given by:

$$\mathcal{L}_{I_z}(s) = \exp \left(-2\pi\lambda \int_r^\infty \left(1 - \int_0^\infty \frac{1}{1 + su^{\frac{\alpha\epsilon}{2}} x^{-\alpha}} \pi\lambda e^{-\lambda\pi u} du \right) x dx \right). \quad (21)$$

We plot the uplink coverage probability using this expression of the Laplace transform and compare it with the numerically computed coverage probability for a simulated PPP under true power control (without independence assumption) in Fig. 5(a) and Fig. 5(b) with no noise and $\lambda = .25$ for $\alpha = 4$, $\epsilon = 1$ and $\alpha = 3.25$, $\epsilon = .75$ respectively. We note that the analytical result derived under the independence assumption closely approximates the true power control result for a PPP as well as the results based on simulations utilizing a set of actual base station locations compared to simulations using the grid model.

The results in Fig. 5(a) and Fig. 5(b) are also further compared with a model which approximates inter-cell interference as a log-normal random variable with parameters determined through a numerical fit of the grid model. The log-normal approximation does not capture the shape of the SINR distribution as well as the proposed model. Approaches that combine the interference into a single term that must be empirically estimated cannot be easily parameterized as a function of key network features such as pathloss exponent, base station/user density, or fractional power control. However, since the proposed model is a function of these system parameters we show in Sec. IV it can be used to give insights into system design and performance trends.

B. Comments on Regular (Grid) Model

Grid models are used to model more “regular” base station locations. The most popular model used in prior work places the base stations on a hexagonal grid. While this model has been extremely helpful in the numerical studies of macro-cellular networks, it does not provide analytical tractability. In this subsection, we show that the random spatial model for the mobile user locations along with an appropriately chosen distribution of R_z provides a generative model that enables us to derive analytical expression for the coverage probability that closely approximates the numerically computed results for the grid model.

Approximating hexagons as circles with the same area λ^{-1} , we assume that each base station is located uniformly in a circle of radius $\frac{1}{\sqrt{\pi\lambda}}$ around its corresponding mobile. The radius value is evaluated from the density of the mobile users assuming there is one base station per mobile

user. It is important to note that the only difference between this and the original PPP model is the distribution of R_z , which is assumed to be uniform in $\left[0, \frac{1}{\sqrt{\pi\lambda}}\right]$ to emulate more regular networks. This is essentially the Assumption 3(b) mentioned in the previous section. The density of R_z can be easily evaluated as:

$$f_{R_z}(r_z) = 2\pi\lambda r_z, r_z \in \left[0, \frac{1}{\sqrt{\pi\lambda}}\right]. \quad (22)$$

As shown in Fig. 2, this closely approximates the distribution of R_z in a grid model. Using this density of R_z , we can now compute the Laplace transform of interference which can be expressed as:

$$\mathcal{L}_{I_z}(s) = \exp\left(-2\pi\lambda \int_r^\infty \left(1 - \int_0^\infty \frac{1}{1 + su^{\alpha\epsilon}x^{-\alpha}} 2\pi\lambda u du\right) x dx\right). \quad (23)$$

While our results hold for general pathloss exponents α , power control exponents ϵ , and different noise powers σ^2 , in the case of $\alpha = 4$ and $\epsilon = 1$, the expression for the Laplace transform can be found in closed-form. In this case, closely corresponding to an interference-limited urban cellular deployment scenario [31], the Laplace transform is given as

$$\mathcal{L}_{I_z}(T) = \exp\left(-\frac{\pi\lambda}{2\sqrt{T}} \left(\pi\lambda \arctan\left(\frac{\sqrt{T}}{\pi\lambda r^2}\right) r^4 - \frac{T}{\pi\lambda} \arctan\left(\frac{\pi\lambda r^2}{\sqrt{T}}\right) - \frac{r^2}{\sqrt{T}} + \frac{T}{2\lambda}\right)\right). \quad (24)$$

We compare the coverage probability derived using this Laplace transform with the numerically computed coverage probability using true power control in a grid model in Fig. 5(a) and Fig. 5(b) with $\lambda = .25$ and $\sigma^2 = 0$ for $\alpha = 4$, $\epsilon = 1$ and $\alpha = 3.25$, $\epsilon = .75$. Surprisingly, we note that the analytical result derived using a random spatial model under the independence assumption in both cases closely approximates the true power control result for a hexagonal grid model even compared to the log-normal interference approximation. As with the PPP model, a crucial step is to appropriately choose the the distribution of R_z . Thus, while utilizing the same underlying random spatial model for the mobile user locations, we are able to “tune” the results to fit a range of highly non-uniform to very regular network topologies.

IV. SYSTEM DESIGN APPLICATIONS

Based on the framework developed in Sec. III, we analyze performance metrics in the context of realistic parameters for modern networks and gain insight into the system design. Here we primarily focus on the scenario of Sec. III-A where the base station is located uniformly in

the Voronoi cell of its corresponding mobile user and the nearest base station distance in this case is Rayleigh distributed. This is useful in capturing the non-uniform topology of many modern network deployments, although similar analysis could be performed using the uniform-distribution based power control approach.

A. Average rate

The use of link-adaptive algorithms in modern cellular networks allows the average SINR to be directly related to average data rate for mobile users. A straightforward application of the results of Sec. III is to determine analytical expressions for user rate under different stochastic power control models as a function of the key uplink parameters, something previously not possible with deterministic network topology models.

Assuming adaptive modulation and coding, we define the average data rate based upon the Shannon capacity expression, $\bar{\tau}(\lambda, \alpha, \epsilon) = \mathbb{E}[\ln(1 + \text{SINR})]$, integrating over the SINR and fading distributions. For the sake of convenience, we give the results in units of nats/Hz, where 1 bit = $\log_e(2)$ nats.

Theorem 2 (Uplink average rate): The average rate of a randomly chosen uplink user is given by

$$\bar{\tau}(\lambda, \alpha, \epsilon) = \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} \int_0^\infty e^{-(e^t-1)r^{\alpha(1-\epsilon)}\sigma^2} \mathcal{L}_{I_z}((e^t-1)r^{\alpha(1-\epsilon)}) dt dr, \quad (25)$$

where $\mathcal{L}_{I_z}(s)$ is given by (17).

Proof: Starting from the definition of $\bar{\tau}$ and SINR,

$$\begin{aligned} \bar{\tau}(\lambda, \alpha, \epsilon) &= \mathbb{E}[\ln(1 + \text{SINR})] \\ &= \int_0^\infty \int_0^\infty \mathbb{P}[\ln(1 + \text{SINR}) > t] dt f_R(r) dr \end{aligned} \quad (26)$$

$$= \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} \int_0^\infty \mathbb{P}\left[\ln\left(1 + \frac{g(r^{\alpha(\epsilon-1)})}{\sigma^2 + I_z}\right) > t\right] dt dr \quad (27)$$

$$= \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} \int_0^\infty \mathbb{P}\left[g > \frac{(e^t-1)(\sigma^2 + I_z)}{r^{\alpha(\epsilon-1)}}\right] dt dr \quad (28)$$

$$= \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} \int_0^\infty e^{-(e^t-1)r^{\alpha(1-\epsilon)}\sigma^2} \mathbb{E}_{I_z}\left[e^{-(e^t-1)r^{\alpha(1-\epsilon)}I_z}\right] dt dr \quad (29)$$

$$= \int_0^\infty 2\pi\lambda r e^{-\pi\lambda r^2} \int_0^\infty e^{-(e^t-1)r^{\alpha(1-\epsilon)}\sigma^2} \mathcal{L}_{I_z}((e^t-1)r^{\alpha(1-\epsilon)}) dt dr, \quad (30)$$

where the derivation of $\mathcal{L}_{I_z}(s)$ follows Theorem 1 and has either the form of (21) or (23) depending on whether the Rayleigh or uniform assumption on the distribution of R_z is made. ■

In Fig. 6 we plot the average user rate expressions using the Rayleigh assumption for R_z as a function of ϵ for pathloss values of $\alpha = 2.5, 3.25$, and 4 and no noise or $\sigma^2 = -104\text{dBm}$. The average rate increases with α as well as the range of values over all values of ϵ . Since the computed average rates are for a randomly chosen user anywhere in the network, the effects of power control on the high, medium, and low SINR users is combined into a single value. Thus as ϵ increases, the rate decreases due to the loss in rate for some users whose transmit power is reduced on average not being overcome by the reduction in interference and increased rate for some users, especially those near the cell-edge. We also note that for a dense deployment with $\lambda = .24$ base station/km² the no noise approximation is very tight.

B. Downlink vs. Uplink Coverage

Another immediate application of the model is to consider the difference in coverage between the downlink and the uplink for the same network topology. We consider the randomly chosen user's SINR distribution in the downlink based on the model presented in [15] for a network whose BSs are distributed according to a PPP with density λ . Before we make the comparison, it is important to highlight that the base station distribution in the proposed uplink model is not PPP, simply by the way it is constructed from the point process of the mobiles. Although an interesting problem in itself, the goal is not to characterize the base station point process and hence we numerically compare the downlink SINR distribution of the following two cases to justify the direct comparison of the uplink results proposed in this paper with the downlink results of [15]:

- Downlink: User-PPP: This corresponds to the case where we start with the base station locations that result from the proposed uplink location model, i.e., the mobiles form a PPP and each base station is located uniformly in the Voronoi cell of the mobile it is serving. The downlink SINR is then numerically evaluated at a randomly chosen mobile user assuming all the base stations transmit at the same power.
- Downlink: BS-PPP: In this case, we consider the randomly chosen user's SINR distribution in the downlink based on the model presented in [15] where the base station locations are

modeled as a PPP with density λ . The coverage probability assuming all the base stations transmit at the same power is

$$p_c(T, \lambda, \alpha) = \pi\lambda \int_0^\infty e^{-\pi\lambda v(1+\rho(T,\alpha)) - \mu T \frac{\sigma^2}{P} v^{\alpha/2}} dv, \quad (31)$$

where

$$\rho(T, \alpha) = T^{2/\alpha} \int_{T^{-2/\alpha}}^\infty \frac{1}{1+u^{\alpha/2}} du. \quad (32)$$

In Fig. 7, we plot the SINR distribution for both these cases and observe that the two models are close enough to facilitate the direct comparison of the downlink analytical results derived in [15] and the uplink ones derived in this paper.

The downlink which assumes constant power transmissions across the network, has two major terms. The first term based is on $\rho(T, \alpha)$ and is not dependent on transmit power and represents the interference-limited contribution to the SINR, while the second term depends on the noise power σ^2 and transmit power P , representing the noise-limited part of the SINR. However, the use of fractional power control in the uplink significantly changes the shape of the distribution of the interference power. This can be seen in both the noise-limited term with σ^2 and the Laplace transform of the interference, which are dependent on ϵ and the distribution of R_z since the transmit powers of the mobiles throughout the network are not constant, but highly variable unlike the downlink.

Fig. 7 plots the two cases with the system parameters given in Table I, which are standard assumptions for a LTE-based cellular network [36], [39], [42]. We first note the gap between the downlink results based on the BS-PPP and User-PPP assumptions is not very large which is reasonable given the prior evaluation of Assumption 2(a). Secondly we consider the disparity between the SINR distributions, especially for large SINR values. One reason for the uplink's lower coverage is due to the mismatch in transmit power compared to the downlink. Additionally at the high SINR values, the use of larger ϵ values also impacts the coverage probability since the users closest to their serving base stations greatly reduce their transmit power relative to the users at the edge of the cell. The impact of ϵ is investigated in further detail in the following section.

The notion of disparate uplink and downlink coverage regions has fundamental consequences on the system design of these cellular networks, different from those of wireless LANs for example which have much smaller coverage regions and typically do not have as significant

hardware distinctions between the different network devices. For example scenarios wherein the mobile user may be able to decode the downlink transmissions, but unable to connect via the uplink will impact handoff algorithms between base stations. One advantage of having a unified framework for uplink and downlink coverage is the ability to evaluate and optimize as function of the relevant system parameters. The aim may be to determine network and system parameters such that the uplink and downlink are balanced or investigating tradeoffs between capacity and coverage enhancements at the base station and mobile terminal respectively.

C. Fractional Power Control

As mentioned previously, the primary motivations for fractional power control in the cellular uplink are to provide beneficial coverage improvements for the lowest-percentile users, who are typically at the cell-edge, and to manage average transmit powers of battery-powered mobile devices. In practical cellular systems such as LTE, fractional power control parameters are network-specific and not user-specific, thus there needs to be some optimization performed to select parameters that can provide acceptable performance for the majority of users and provide a high overall system capacity [30], [31]. Fig. 8 gives the coverage probability distributions as a function of the fractional power control factor ϵ for a network topology given by Table I. The baseline case of fixed transmit power for all users ($\epsilon = 0$) does not provide the lowest overall coverage probabilities, but does provide the greatest coverage probability for the highest SINR thresholds. The largest coverage probability for users in the lower 50 percentile is given by $\epsilon = 0.25$, followed by $\epsilon = 0.5$, giving gains over fixed transmit power before crossing below the $\epsilon = 0$ curve at 5 and 0 dB respectively. We also note that for the very lowest SINR thresholds < -10 dB, the difference in coverage probability for $\epsilon = 0, 0.25$, and 0.5 is negligible. As ϵ increases, the coverage probability curves shift lower with $\epsilon = .75$ providing much lower coverage probability than fixed transmit power, especially for SINR thresholds > 5 dB. Full pathloss inversion, $\epsilon = 1$ power control shows an even more significant reduction in coverage across all SINR thresholds.

In Fig. 9 we plot the value of ϵ which maximizes the coverage probability for a given SINR target T , denoted as $\hat{\epsilon}$ for $\alpha = 2.5, 3.2$, and 3.7 . In other words, the value of $\hat{\epsilon}$ is determined

according to

$$\hat{\epsilon}(T, \alpha, \lambda) = \arg \max_{\epsilon} 2\pi\lambda \int_0^{\infty} r e^{-\pi\lambda r^2 - Tr^{\alpha(\epsilon-1)}\sigma^2} \mathcal{L}_{I_z}(Tr^{\alpha(1-\epsilon)}) dr, \quad (33)$$

where the Laplace transform of the interference is given by (7).

This gives insight into the selection of ϵ based on solely on a coverage probability maximizing basis. An interesting observation is that there are two distinct regions denoted in each plot by plateaus of near constant $\hat{\epsilon}$. For users with low SINR a moderate value of $\epsilon = .25$ to $.3$ provides the greatest gains while for users with high SINR, the SINR is maximized by transmitting with the maximum power and $\epsilon = 0$. We note that there is some sensitivity to the pathloss exponent α , in all three cases, the transition between the two regions is fairly steep in its slope, with an approximately 5 dB range, while as α increases the $\hat{\epsilon}$ for the low SINR region decreases while the SINR transition threshold between the two regions increases slightly. Additionally, this dual-regime behavior for fractional power control in uplink cellular networks differs from the behavior of power control in other classes of wireless networks, notably ad-hoc wireless networks, which were shown to have an optimal value of $\epsilon = .5$ [43], [44].

These observed effects of fractional power control in Fig. 8 and Fig. 9 can be understood by focusing on the gains perceived by users close to their desired base station relative to those at the edge and their interdependency. Cell-interior users typically experience good RF conditions and are not as susceptible to interference as users at the cell edge. Instead, they are more noise-limited which means a reduction in their transmit power reduces their achievable SNR. This is especially true under pathloss-based power control, since high values of ϵ reserve the greatest transmit power for users with large pathloss. Thus transmitting at full power ($\epsilon = 0$) is the SINR-optimizing strategy.

Cell-edge users, however, are more fundamentally interference limited, and the use of pathloss-proportional power control results in a decrease in the transmit power of interfering cell-center users and a relative increase in their transmit power (to overcome the larger cell-edge pathloss) benefiting their SINR. This disparity becomes more pronounced with high ϵ . As a result, there is a complex trade off in the reduction of interference from neighboring cell-center users and increased interference by mobiles at the cell edge which gives rise to the observed intermediate range of ϵ values providing the highest gains for the majority of users. In effect, full-inversion power control performs a reordering of SINRs between cell-edge and cell-interior users which

does not provide system-wide gains. An advantage of the PPP uplink cellular model is that it captures the relevant system and topology parameters necessary for system designers to determine operating thresholds for a given range of parameters.

Fig. 10 gives the overall transmit power utilization of mobiles in the network as a function of ϵ with a maximum transmit power of 23 dBm and an average transmit power of $\mu^{-1} = 10$ dBm. Clearly the transmit powers of the mobile users are greatly reduced with the introduction of power control. For high values of ϵ we note that 10-15% of the users have transmit power less than 0 dBm, which is a 23 dB reduction in power compared to the maximum transmit power. For this reason, proposed system guidelines for the uplink may wish to choose ϵ to balance the metrics of coverage and battery utilization.

V. CONCLUSION

This work has presented tractable expressions for the coverage probability and average rate in the cellular uplink which are applicable to uniform and irregular network topologies. The expressions are based on a novel analytical model utilizing the spatial Poisson process and are solely a function of the network topology and system design parameters including SINR targets, base station density, and fractional power control parameters. The presented results provide insight into the differences of downlink and uplink performance expectations and the tradeoff between using fractional power control to benefit cell-edge users and reducing overall power utilization by mobiles.

A major arena for future work is to understand how these dynamics are enhanced or differ for heterogeneous network topologies [18], [45]. The nested and overlapping nature of coverage regions for multiple tiers of access points is expected to have a large impact on the overall interference distribution and a range of hardware requirements and use cases may lead to unique system design tradeoffs not experienced in single-tier networks.

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TABLE I
SYSTEM PARAMETERS

Bandwidth	10 MHz
base station density	.24 BS/km ²
User distribution	uniform
Pathloss (dB)	$37 \log(d)$, d = distance in meters
Downlink Tx Power	45 dBm (30 W)
Uplink Max Tx Power	23 dBm (200 mW)
FPC ϵ	0.6, 0.8, 1.0
Noise Power Density	-174 dBm/Hz

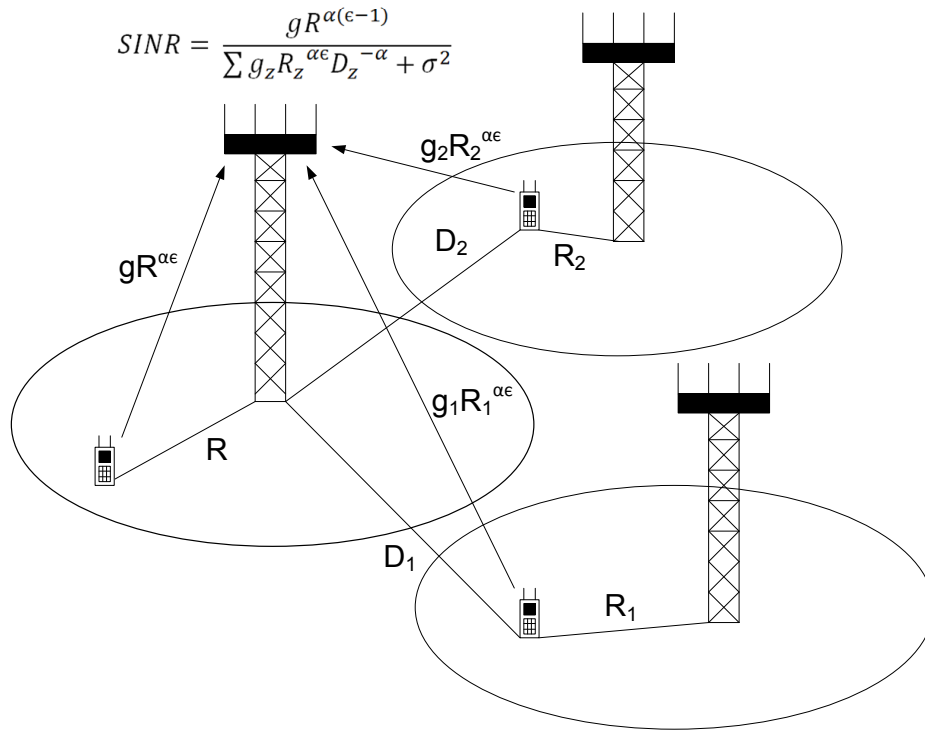


Fig. 1. Visual system model example giving the SINR at the typical base station, focusing on the serving mobile and two interfering mobiles in adjacent cells.

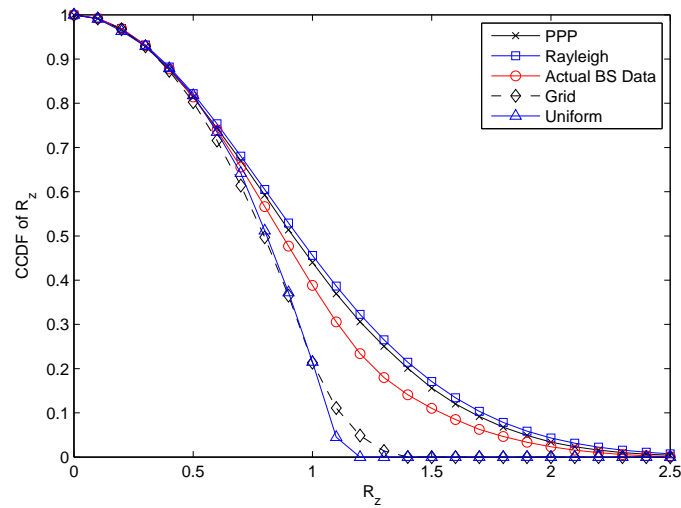


Fig. 2. A comparison of the CCDFs of R_z both for the PPP and a grid model with their respective approximations for $\lambda = 1/4$. Also included is the CCDF of R_z for a set of real base station locations of an urban 4G network.

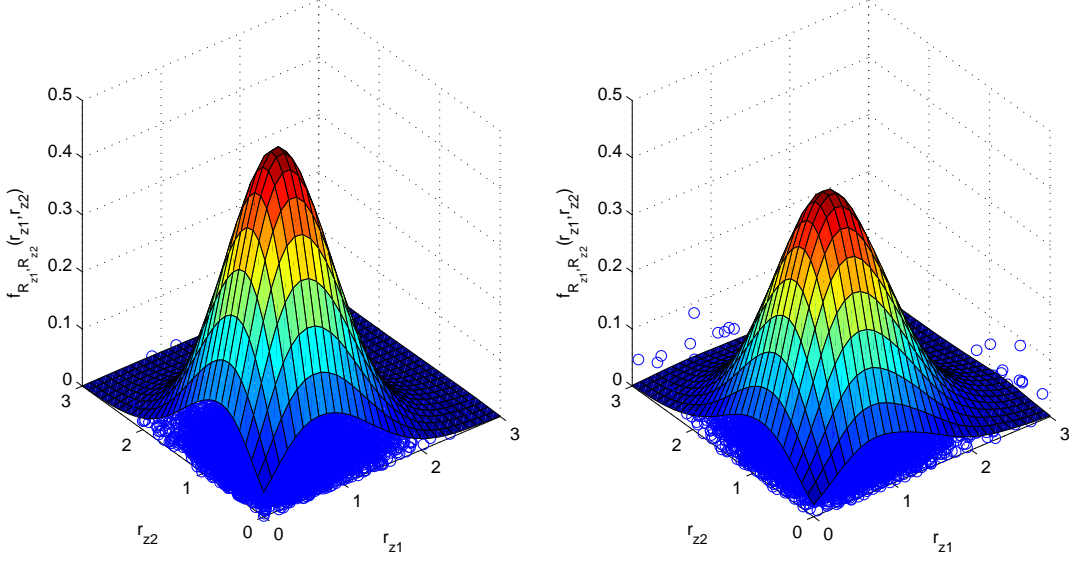


Fig. 3. Joint densities of R_{z_1} and R_{z_2} for the actual PPP model (left) and under the independence assumption (right). R_{z_1} and R_{z_2} are the distances of the mobiles to their respective base stations in two neighboring Voronoi cells.

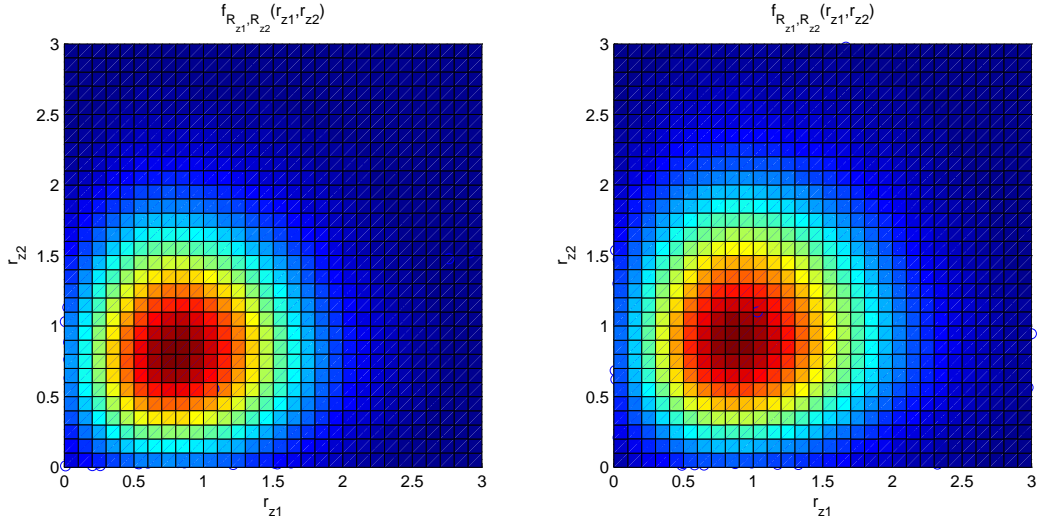


Fig. 4. Top view of the joint densities of R_{z_1} and R_{z_2} for the actual PPP model (left) and under the independence assumption (right). R_{z_1} and R_{z_2} are the distances of the mobiles to their respective base stations in two neighboring Voronoi cells.

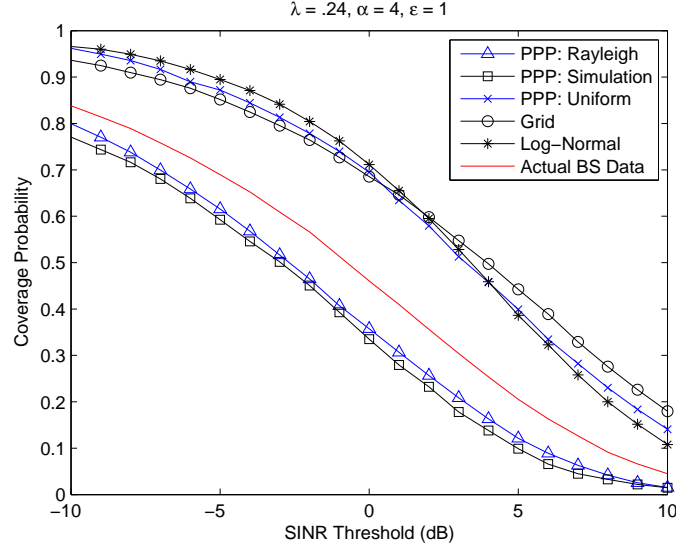
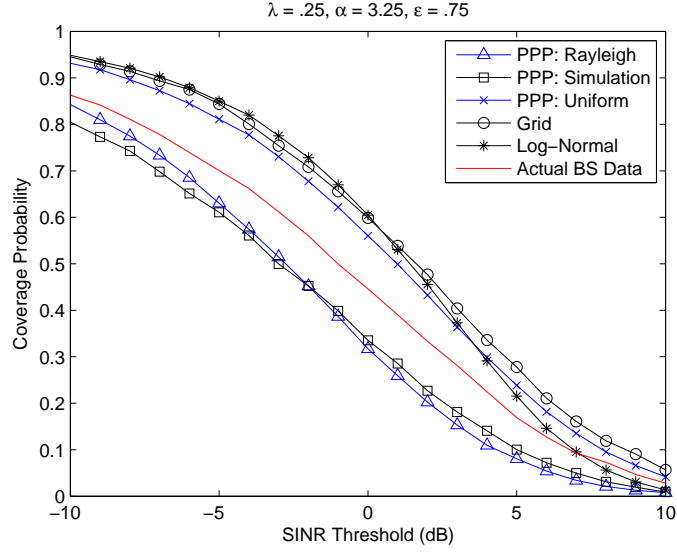
(a) $\alpha = 4, \epsilon = 1$ (b) $\alpha = 3.25, \epsilon = .75$

Fig. 5. A comparison of the uplink coverage probability for the proposed model utilizing Rayleigh-distributed and Uniform-distributed R_z with simulations for the grid and the PPP models. Also included is the result using a set of actual base station locations and results using a log-normal approximation for the interference.

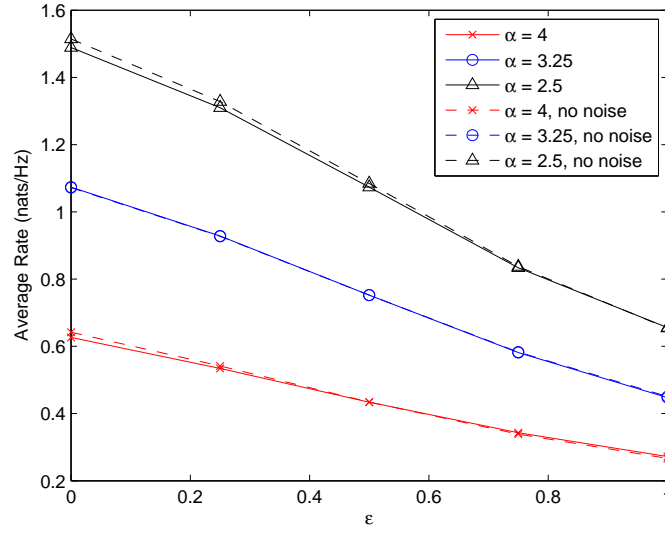


Fig. 6. Average user rate as a function fractional power control parameter ϵ for pathloss exponents $\alpha = 2.5, 3.25$, and 4 and $\lambda = .24$ and with no noise or with $\sigma^2 = -104\text{dBm}$.

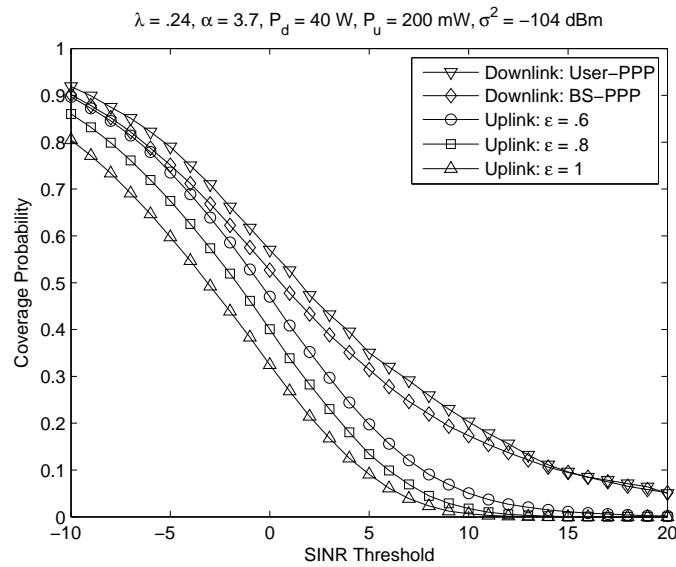


Fig. 7. A comparison of the coverage probability for the downlink with 40W transmit power and the uplink utilizing fractional power control with $\epsilon = .6, .8$ and 1 , and a max transmit power of 200 mW .

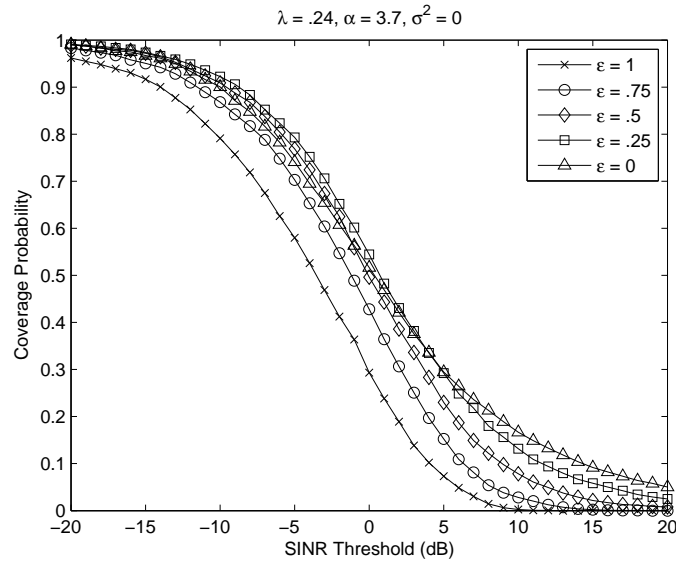


Fig. 8. A plot of the uplink coverage probability for a PPP network with stochastic fractional power control and a range of ϵ values.

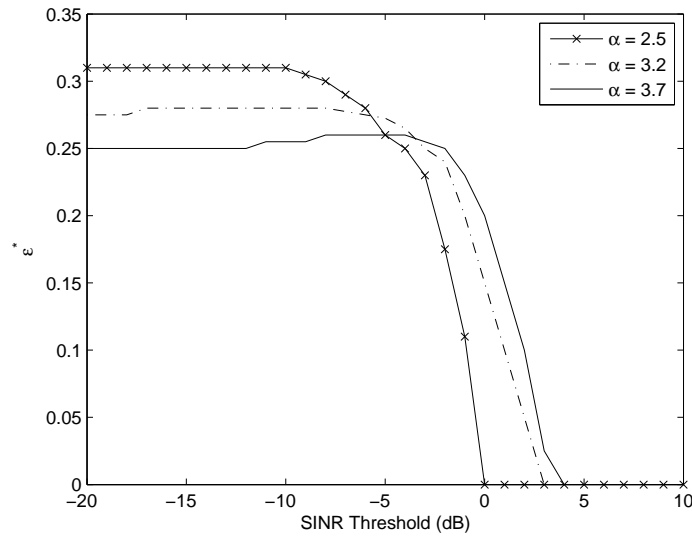


Fig. 9. A plot of the coverage-maximizing $\hat{\epsilon}$ for a given SINR threshold value, $\lambda = .24$, and $\alpha = 2.5, 3.2$, and 3.7 .

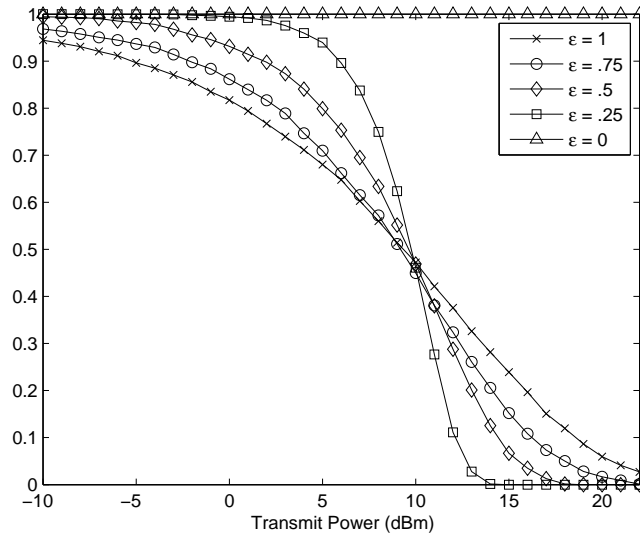


Fig. 10. The CCDF of the average transmit power per mobile as a function of ϵ with $\lambda = .24$, $P_{max} = 23\text{dBm}$, $\mu^{-1} = 10\text{dBm}$, and $\alpha = 3.7$ pathloss factor.